

Cartographically Plausible Label Placement

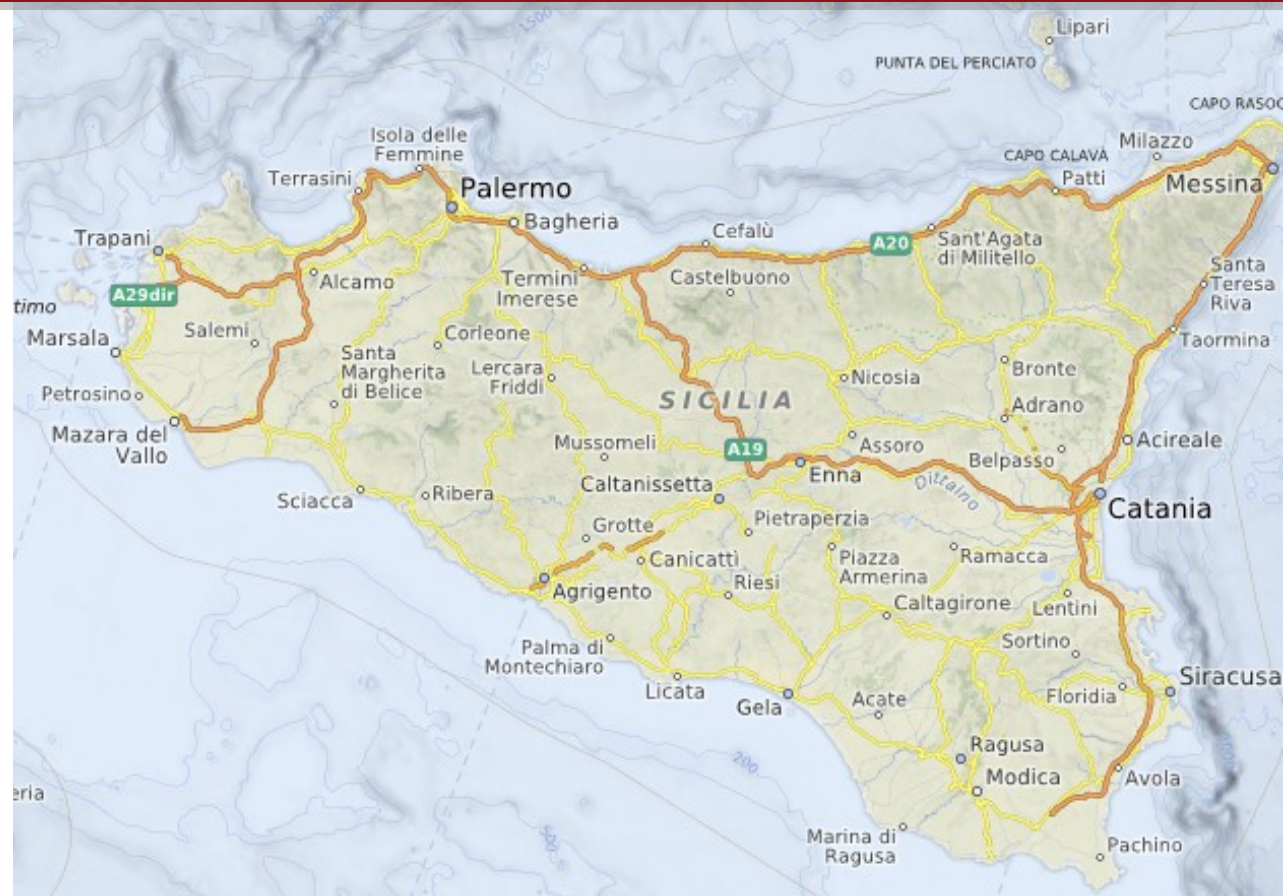
A Multi-criteria Model for Good Point-label Placement on OSM Maps

Maxim Rylov

Andreas Reimer



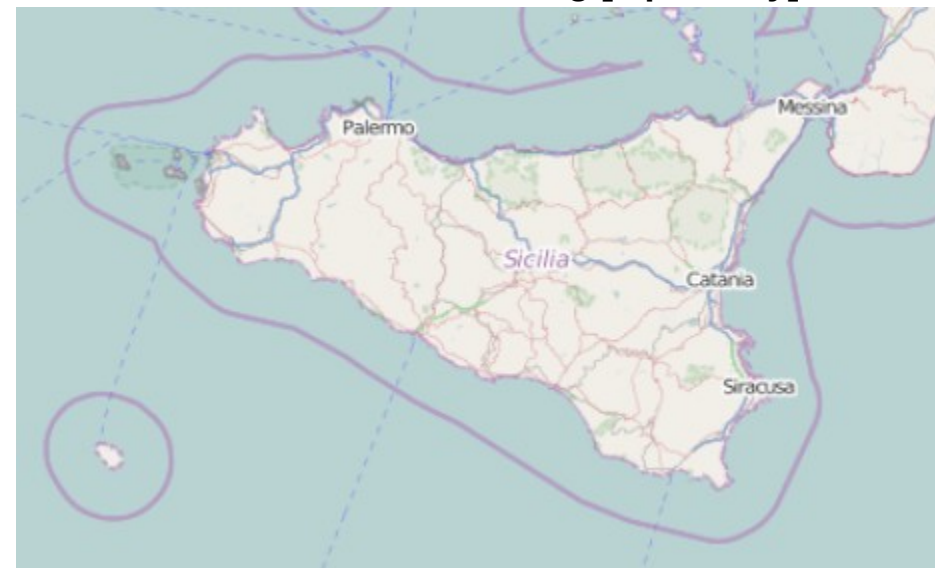
UNIVERSITÄT
HEIDELBERG
ZUKUNFT
SEIT 1386



Motivation and goals

- Labeling on automatically generated maps is poor and untidy.
- Develop a model that considers all cartographic guidelines.
- Apply the proposed model to label a world map using OSM data.
- Present much more data on OSM maps

Automated lettering [5 pts only]



SOURCE: OpenStreetMap.org

Manual lettering [54 + polygons]

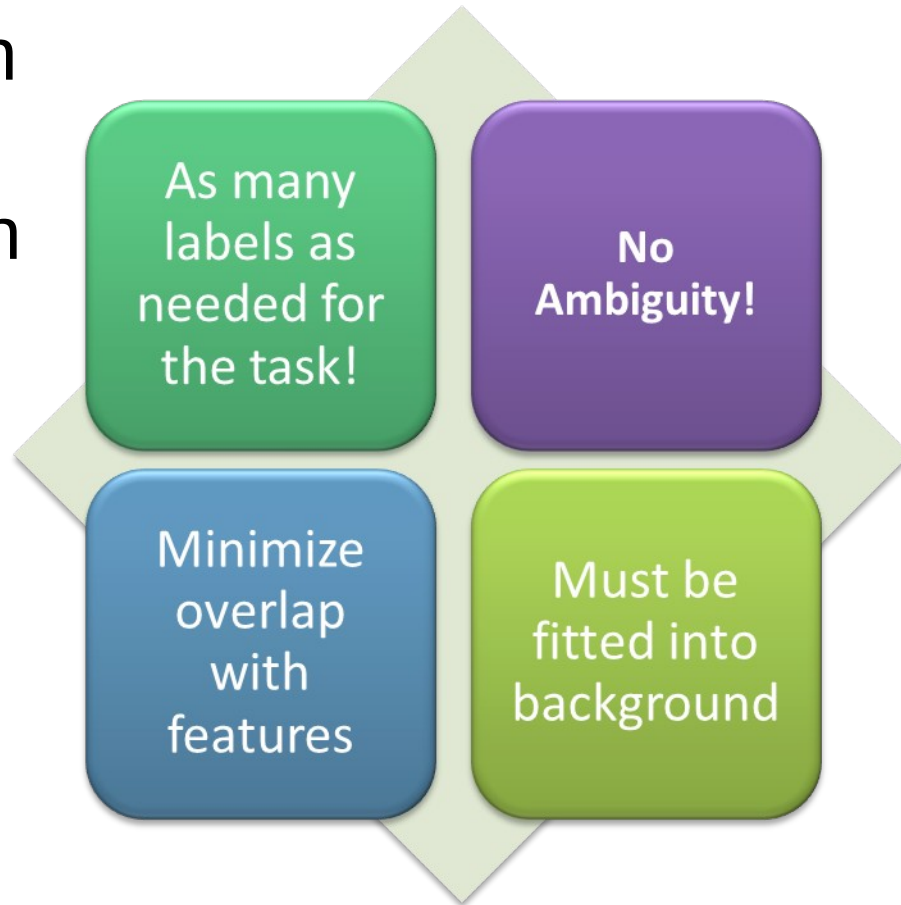


SOURCE: Encyclopædia Britannica World Atlas

Purpose:

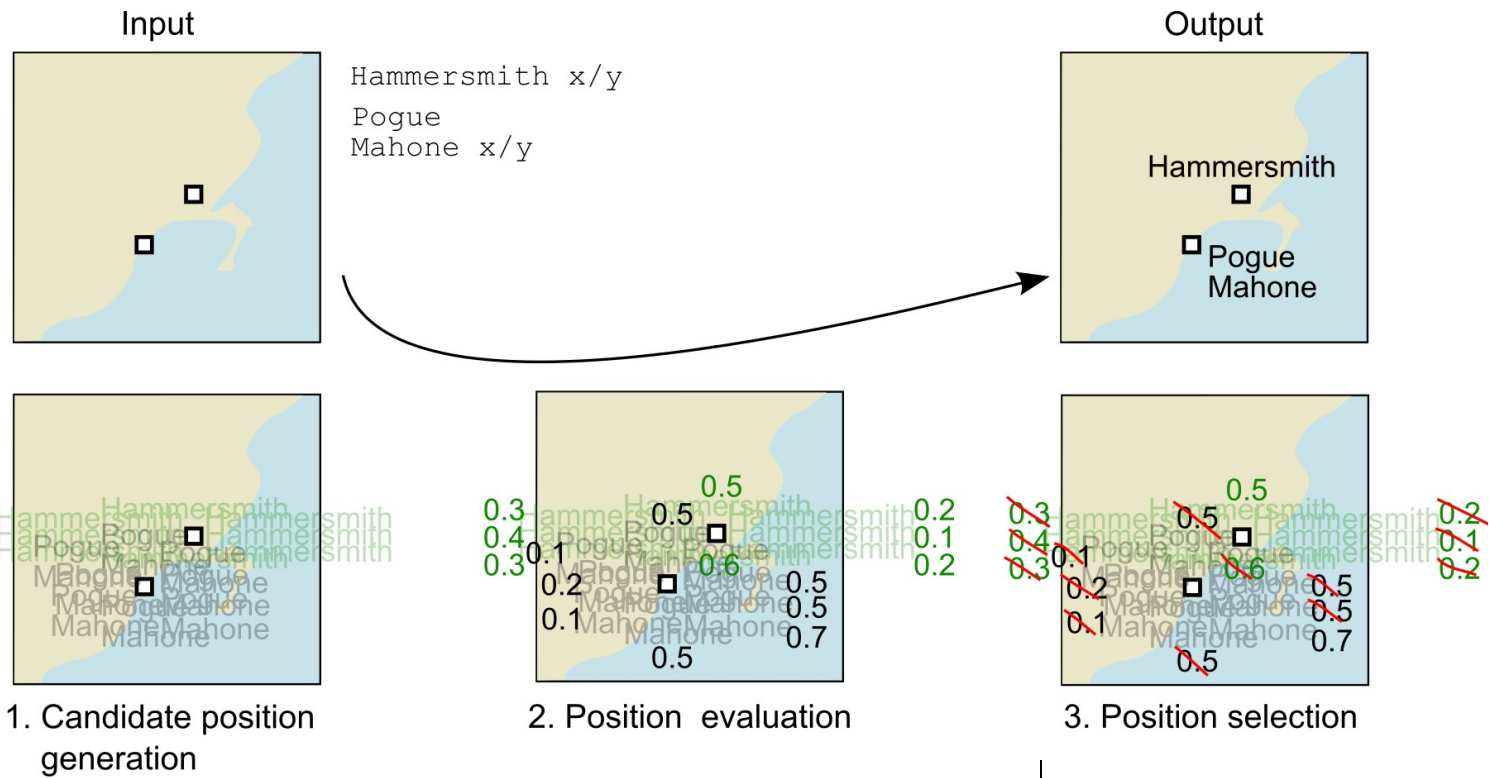
Quantification
Orientation
Differentiation

Constraints



Source: Imhof, E 19

Label placement subtasks



Positioning around symbol Feature priority

- Background feature overlap
- Cluttering
- Disambiguation
- Coastal places

Greedy algorithm

- Simulated Annealing
- Genetic algorithm
- Tabu Search algorithm
- Artificial intelligence proced.



Multi-criteria model

$$\text{Maximize } Q(x) = \sum_{i=1}^{P_n} \sum_{j=1}^N \left(\beta_1 F_{i,j}^{prior} + \beta_2 F_{i,j}^{pos} + \beta_3 F_{i,j}^{over} \right. \\ \left. + \beta_4 F_{i,j}^{disamb} + \beta_5 F_{i,j}^{clut} + \beta_6 F_{i,j}^{coast} \right) x_{i,j}$$

$$\text{Subject to } \sum_{i=1}^{P_n} x_{i,j} \leq 1, \forall j = 1..N.$$

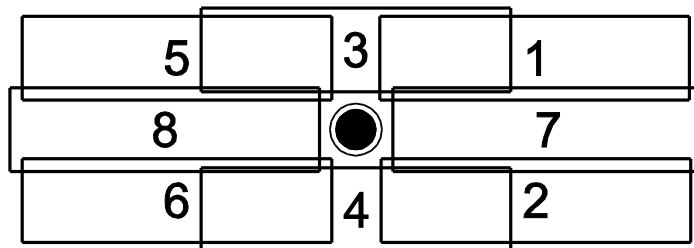
$$\text{and } x_{i,j} + x_{k,m} \leq 1$$

BORING

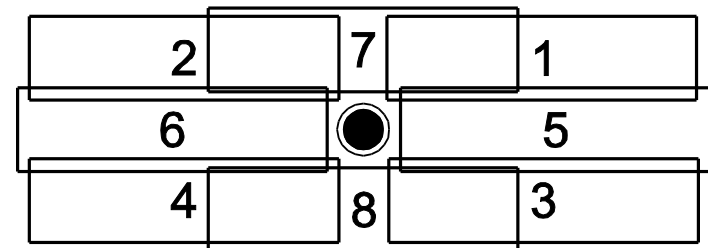
where $x_{i,j} \in \{0,1\}, \forall i = 1..P_n, \forall j = 1..N$, N – the number point features, P_n – number of positions, $F_{i,j}$ are metrics that represent cartographic preferences of label placement.

Positioning metric

- Optical coincidence
- Legibility
- Ascending and descending letters



(a)



(b)

Commonly used models for positional prioritization

Priority metric

- Population
- Importance
- Administrative status

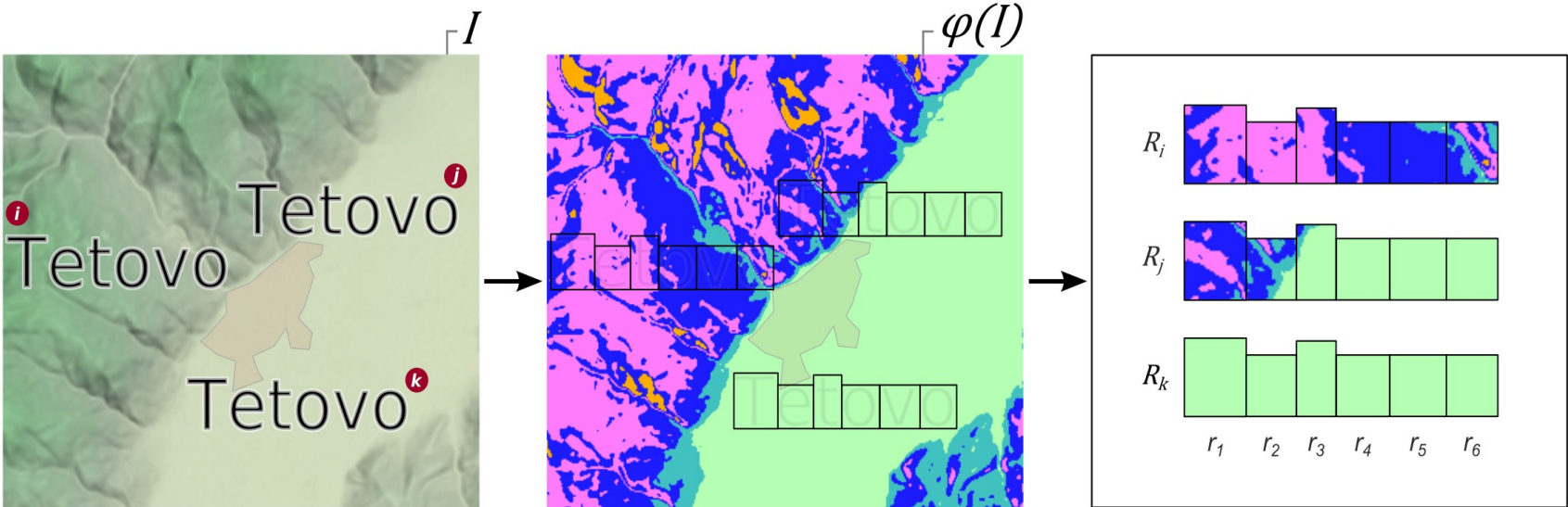


Frankfurt am Main (~690,000)
Worms (~80,000).

OSM tags:
place=*
population=*

Feature overlap metric

- Create a raster image with background information (e.g., road network, water bodies, shaded relief).
- Apply image segmentation algorithm (reduce number of colours).
- Perform analysis to detect homogeneous regions.



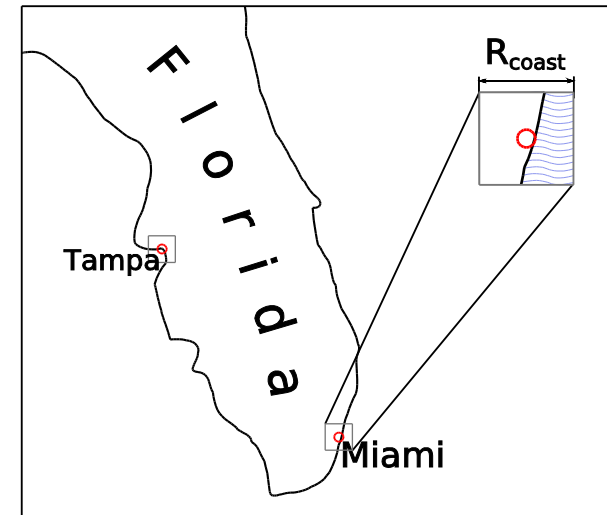
Coastal place metric

Requirements:

- Datasets usually lack coastal place attribute.
- The point-shore relationship is scale-dependent.

Approach methodology:

- Coastline dataset
- Define the neighborhood of a place.
- Compute area of water.
- Decide whether it is a coastal place or not.



Comparison of label placement



Number of labels: 5

Source: OpenStreetMap.org



Number of labels: 12

Source: Mapbox Streets



Number of labels: 54

Source: Google Maps



Number of labels: 55

Source: Proposed model using OSM data



Experimental results

Tested region: northern part of Denmark

Metrics	Solver	Labels	Quality	Time [s]
Priority + Positioning (2/6)	Greedy	59 (71.95 %)	0.617	0.019
All (6/6)	Simulated Annealing	74 (90.24 %)	0.834	3.569

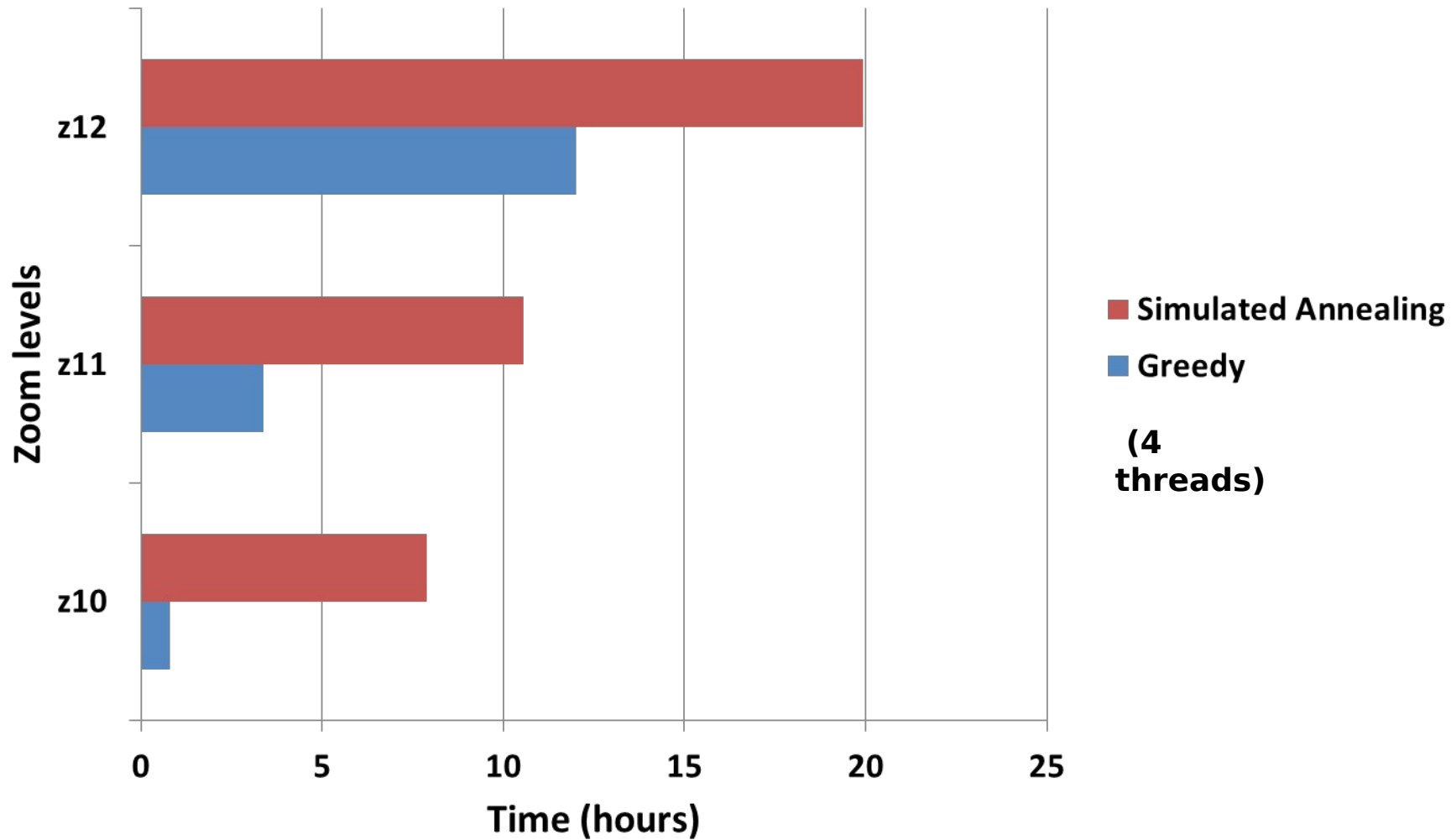
Performance and quality depends on:

- Number of input labels
- Number of quality metrics
- Solving algorithm

Pros and cons:

- High cartographic quality
- SA gives 7% more labels
- Time-consuming and resource-intensive task

Experimental results



- Detailed description of the model
Rylov, M. and Reimer, A. 2014 “**A Comprehensive Multi-criteria Model for High Cartographic Quality Point-Feature Label Placement**”, *Cartographica*, 49(1): 52-68.
- The model can be reproduced in your own solution or in Mapnik, GeoServer, Mapserver, etc.
- A map with a sophisticated label placement for the whole globe
<http://openmapsurfer.uni-hd.de> (OSM Roads layer)
- The proposed model is implemented within the **MapSurfer.NET** framework
<http://openmapsurfer.uni-hd.de/Framework/info.html>

Thanks for your attention!

Maxim Rylov

maxim.rylov@geog.uni-heidelberg.de

Heidelberg University
Institute of Geography
Chair of GIScience

<http://giscience.uni-hd.de>

